

PCAN-TJA1054

Bus Converter High-Speed CAN to
Low-Speed CAN

User Manual



Document version 2.2.0 (2019-06-03)

PEAK
System

Relevant products

| Product Name | Model | Part number |
|--------------|-------|-------------|
| PCAN-TJA1054 | | IPEH-002039 |

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1 Introduction

The PCAN-TJA1054 bus converter establishes a connection between a High-speed CAN bus (ISO 11898-2) and a Low-speed CAN bus (ISO 11898-3). One of the most important potential applications of the bus converter is a simple connection between a PEAK CAN interface (e.g. PCAN-USB) and a Low-speed CAN bus.

Low-speed CAN (LS-CAN)

The LS-CAN is primarily intended for low-speed applications up to 125 kbit/s in passenger cars. Like the High-speed CAN (HS-CAN) the LS-CAN transmits signals differentially through two wires. However, its fault tolerance (e.g. at a short circuit) automatically provides an operation with only a single wire.



Tip: At the end of this manual (Appendix C) you can find a Quick Reference with brief information about the operation of the PCAN-TJA1054.

1.1 Properties at a Glance

- Adapter from High-speed CAN to Low-speed CAN
- Bit rates of up to 125 kbit/s
- CAN transceiver NXP PCA82C251 and TJA1055
- Termination resistors for Low-speed CAN can be switched (560 Ohm / 5.66 kOhm)
- Power LED
- Error LED (Low-speed CAN)

- └ CAN bus connection via D-Sub, 9-pin (in accordance with CiA® 303-1)
- └ Power supply (5 V) through pin 1 of the High-speed CAN connection. Nearly all CAN interfaces by PEAK-System can provide the required supply
- └ Extended operating temperature range from -40 to 85 °C (-40 to 185 °F)



Note: You can find additional information about the properties and the behavior of the LS-CAN transceiver TJA1055 in the corresponding data sheet, which you can download, e.g. from the NXP website: www.nxp.com

1.2 System Requirements

- └ HS-CAN component capable of routing a 5-Volt supply to the CAN connector (can be set for all CAN interfaces from the PCAN series)

1.3 Scope of Supply

- └ Adapter in plastic casing
- └ Manual in PDF format

2 Connectors

2.1 Connecting the High-speed CAN Side

The PCAN-TJA1054 is designed for a direct connection to a HS-CAN component (e.g. PCAN-USB). The HS-CAN side has a 9-pin D-Sub connector. The pin assignment corresponds to the specification CiA® 102.

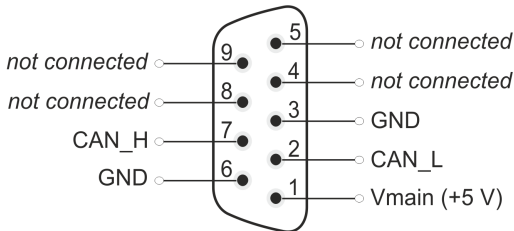


Figure 1: Pin assignment HS-CAN



Attention! Make sure, that the HS-CAN component always is turned off when connecting or disconnecting the PCAN-TJA1054. Otherwise the PCAN-TJA1054 or the connected hardware may be damaged or destroyed.

Between CAN_L and CAN_H a terminating resistor of 60 Ω is installed internally. Therefore an additional line termination is not needed for the connected HS-CAN component.

For power supply the PCAN-TJA1054 uses a direct voltage of +5 V (V_{main}). This must be applied to pin 1 of the HS-CAN connector.



Note: Please see the documentation of the HS-CAN component the PCAN-TJA1054 shall be connected to, to obtain information about a power supply on pin 1.

2.2 Connecting the Low-speed CAN Side

For the connection of the LS-CAN bus a 9-pin D-Sub port is used. The assignment is as follows:

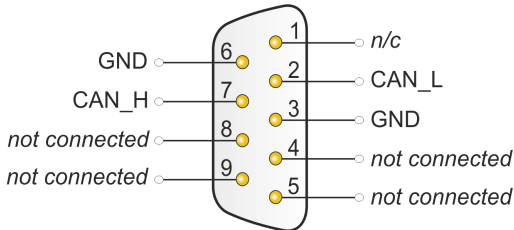


Figure 2: Pin assignment LS-CAN

Bus termination Low-speed CAN

Every node in a Low-speed CAN has a terminating resistor. For optimum system conditions the whole CAN bus should be terminated with $100\ \Omega$ (parallel connection of all terminating resistors). A single node should be terminated with at least $500\ \Omega$ and at most $6\ \text{k}\Omega$.

To simplify the adaptation of the PCAN-TJA1054 to an existing CAN bus you can switch between the terminating resistors $560\ \Omega$ and $5.66\ \text{k}\Omega$ using the slide switch.


For smaller CAN buses or for testing a single component the slide switch should be set to $560\ \Omega$. For monitoring or configuration of existing CAN buses, that are already optimized regarding termination, the slide switch should be set to $5.66\ \text{k}\Omega$ to minimize an influence on the total termination.

3 Operation

3.1 Bit Rate

Make sure that the bit rate of the connected HS-CAN component matches the bit rate of the LS-CAN bus for operating the PCAN-TJA1054. No conversion or automatic adaptation of the bit rate is done in the PCAN-TJA1054.

3.2 Low Power Modes

 **Note:** The LS-CAN transceiver always works with the normal operation mode. The operation in one of the low-power modes "Sleep" or "Standby" is not possible.

Because the PCAN-TJA1054 is connected to further hardware (controllers, for example) only through the CAN bus, it is not capable of activating one of the low-power modes.

If the PCAN-TJA1054 shall be connected to the LS-CAN bus of a motor vehicle, that uses a low-power mode, the following should be considered:

In a low-power mode all transceivers in a motor vehicle terminate CAN_L against the battery. However, the PCAN-TJA1054 still terminates CAN_L against V_{CC} . On CAN_L the voltage adjusts to a level above or below the recognition threshold for short circuits on CAN_L (7.3 V) depending on the network size and termination.

If the voltage on CAN_L stays below 7.3 V, a shunt current leads to an increased current consumption in the motor vehicle.

If however the voltage on CAN_L is above 7.3 V, the PCAN-TJA1054 detects a short circuit on CAN_L and switches to single wire operation (CAN_H). The communication is ensured but an error is indicated by the red LED (see section *3.4 Red Error LED*).

3.3 Status LED

| LED | Meaning |
|-------|--|
| Green | Power, Voltage supply +5 V |
| Red | Error, Error condition on the LS-CAN bus |

3.4 Red Error LED

The red LED indicates the state of the error output of the LS-CAN transceiver. This output is active for the following error conditions on the Low-speed CAN side:

- └ Interrupt on CAN_H
- └ Interrupt on CAN_L
- └ Short circuit between CAN_H and GND
- └ Short circuit between CAN_H and VCC
- └ Short circuit between CAN_L and GND
- └ Short circuit between CAN_L and VCC
- └ Short circuit between CAN_H and CAN_L

Please see the data sheet for the CAN transceiver TJA1055 for further details.

4 Technical specifications

| CAN | |
|----------------|---|
| High-speed CAN | ISO 11898-2 2.0A (standard format) and 2.0B (extended format) Transceiver: PCA82C251 D-Sub socket, 9 pins (in accordance with CiA® 102) Internal bus termination with 62 Ω (fixed) |
| Low-speed CAN | ISO 11898-3 Transceiver: TJA1055 D-Sub plug, 9 pins Internal bus termination with 560 Ω or 5.66 kΩ (switchable) |
| Bit rate | max. 125 kbit/s |

| Power supply | |
|---------------------|---|
| Supply Voltage | +5 V = (via pin 1 of D-Sub socket) |
| Power consumption | Normal operation: 20 – 30 mA At an Error: 40 mA Maximum: 80 mA (peak) |

| Environment | |
|---------------------------------------|-------------------------------|
| Operating temperature | -40 - +85 °C (-40 to 185 °F) |
| Temperature for storage and transport | -40 - +100 °C (-40 to 212 °F) |
| Relative humidity | 15 - 90 %, not condensing |
| Ingress protection (IEC 60529) | IP20 |

| Measures | |
|-----------------|--|
| Size | 50 x 32 x 17 mm See also dimension drawing Appendix B on page 13 |
| Weight | 25 g |

Conformity

| | |
|--------|--|
| EMV | Directive 2014/30/EU DIN EN 55024:2016-05 DIN EN 55032:2016-02 |
| RoHS 2 | Directive 2011/65/EU DIN EN 50581 VDE 0042-12:2013-02 |


Appendix A CE-Certificate

EU Declaration of Conformity



This declaration applies to the following product:

Product name: PCAN-TJA1054
Item number(s): IPEH-002039
Manufacturer: PEAK-System Technik GmbH
Otto-Roehm-Strasse 69
64293 Darmstadt
Germany

 We declare under our sole responsibility that the mentioned product is in conformity with the following directives and the affiliated harmonized standards:

EU Directive 2011/65/EU (RoHS 2)

DIN EN 50581 VDE 0042-12:2013-02

Technical documentation for the assessment of electrical and electronic products with respect to the restriction of hazardous substances;
German version EN 50581:2012

EU Directive 2014/30/EU (Electromagnetic Compatibility)

DIN EN 55024:2016-05

Information technology equipment – Immunity characteristics – Limits and methods of measurement (CISPR 24:2010 + Cor.:2011 + A1:2015);
German version EN 55024:2010 + A1:2015

DIN EN 55032:2016-02

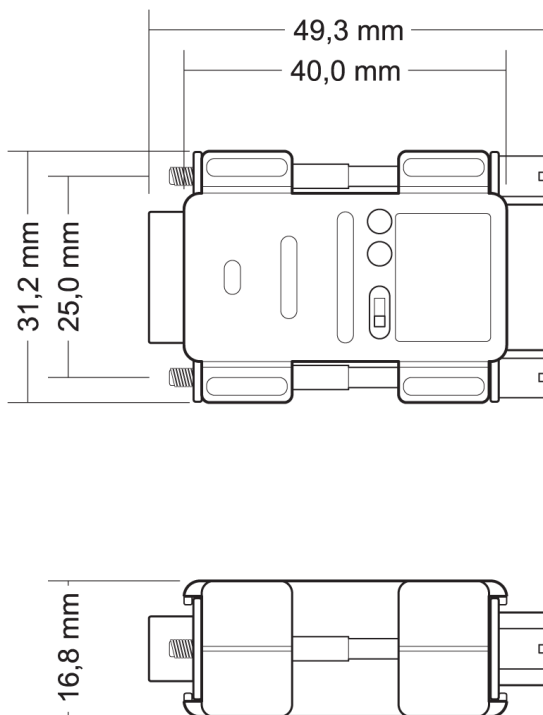
Electromagnetic compatibility of multimedia equipment - Emission Requirements (CISPR 32:2015);
German version EN 55032:2015

Darmstadt, 22 February 2019

A handwritten signature in black ink, appearing to read "Uwe Wilhelm".

Uwe Wilhelm, Managing Director

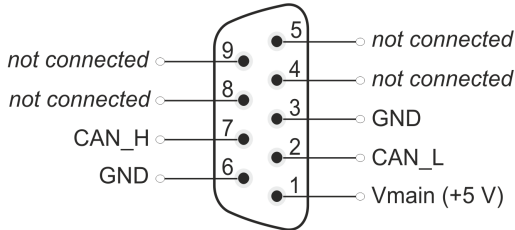
Appendix B Dimension Drawing



The figure doesn't show the actual size of the product.

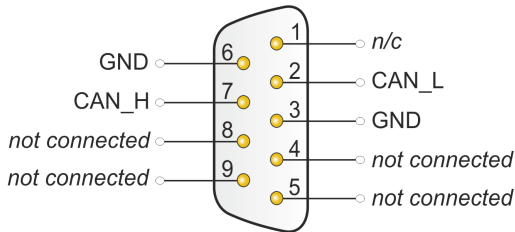
Appendix C Quick Reference

High-speed CAN socket



Connect or disconnect the PCAN-TJA1054 only, when the relevant HS-CAN component is turned off!

Low-speed CAN plug



Slide switch Low-speed CAN termination

- 560 Ω for building smaller networks, testing single components
- 5.66 k Ω for monitoring or configuring existing networks (already terminated optimally)

Status LEDs

| LED | Meaning |
|-------|--|
| Green | Power, Voltage Supply +5 V |
| Red | Error, Error condition on the LS-CAN bus |

Bit rate

Is configured in the connected HS-CAN component. Make sure that the bit rate of the connected HS-CAN component matches the bit rate of the LS-CAN bus for operating the PCAN-TJA1054.